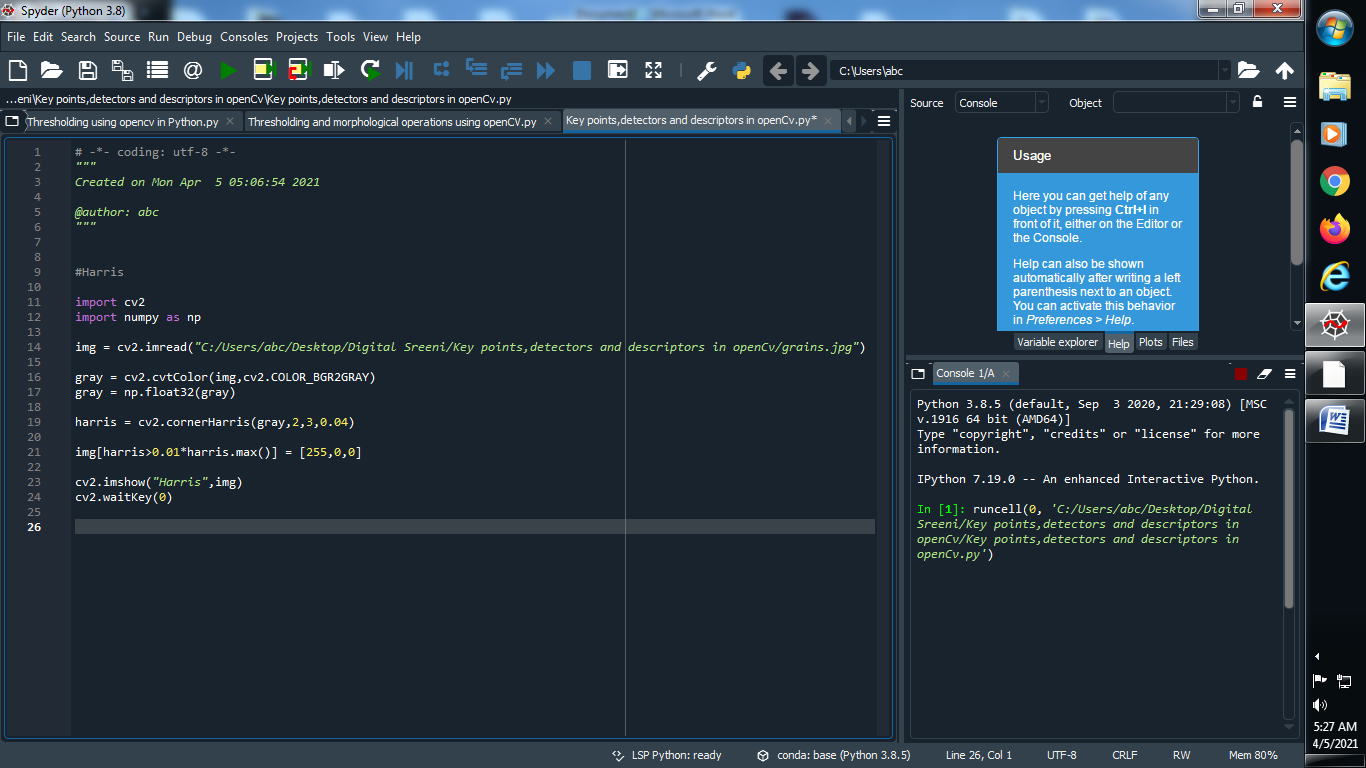
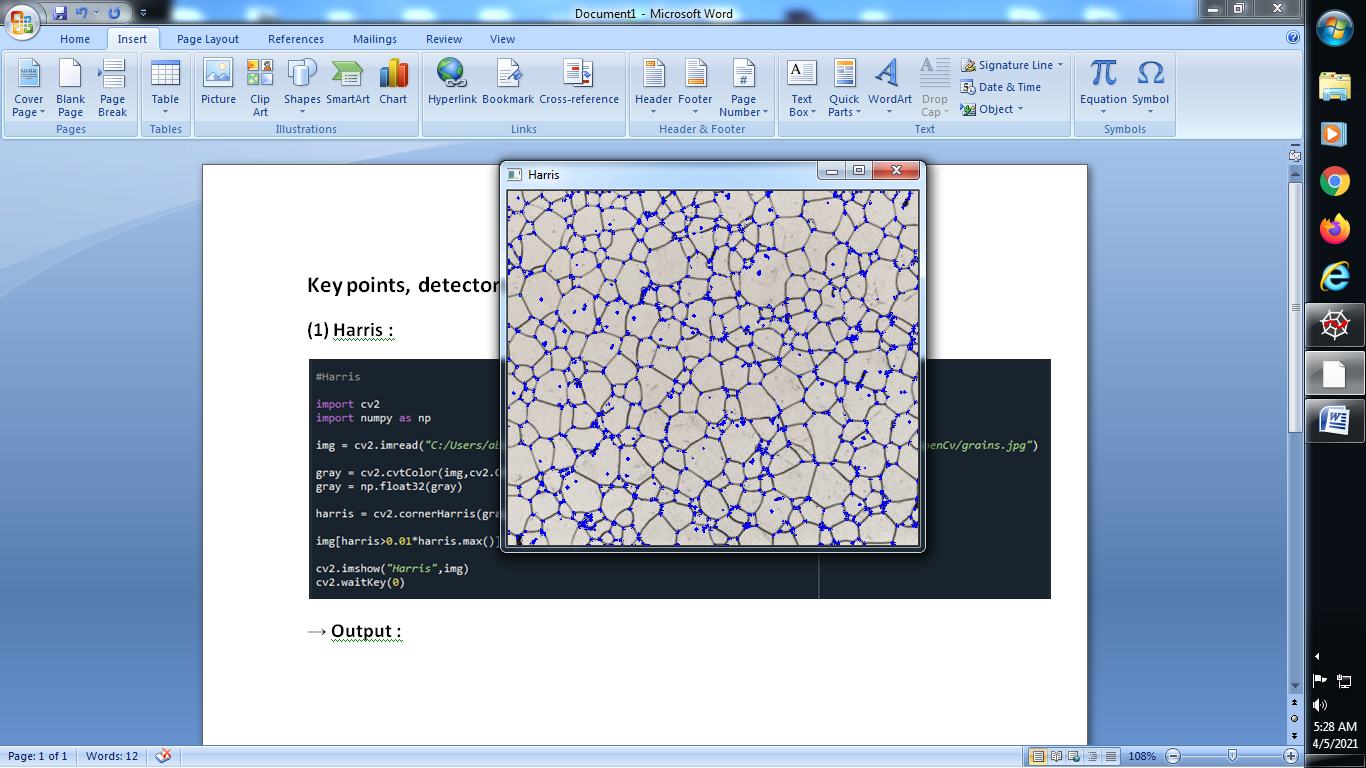
**Key points, detectors and descriptors :**

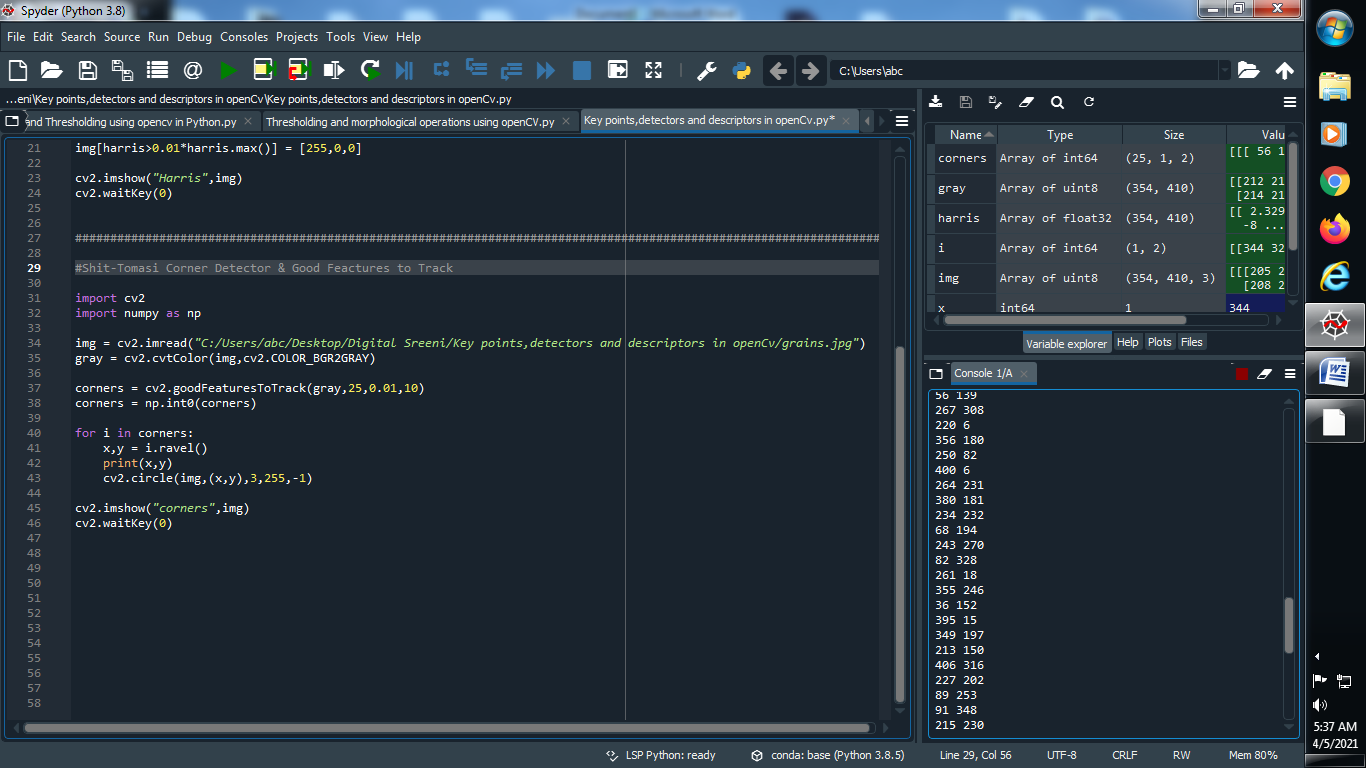
**(1) Harris :**

****

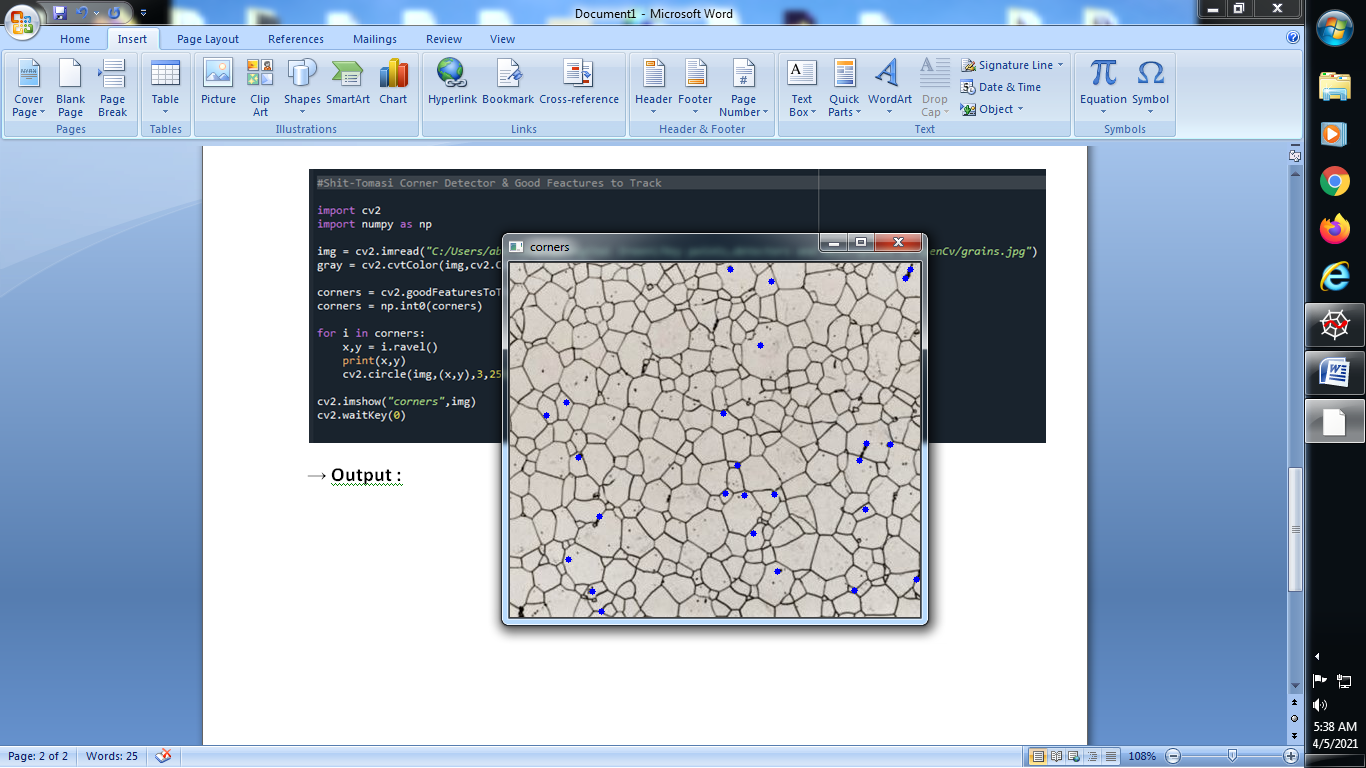
**→ Output :**

****

**(2) Shit-Tomasi Corner Detector & Good Feactures to Track :**

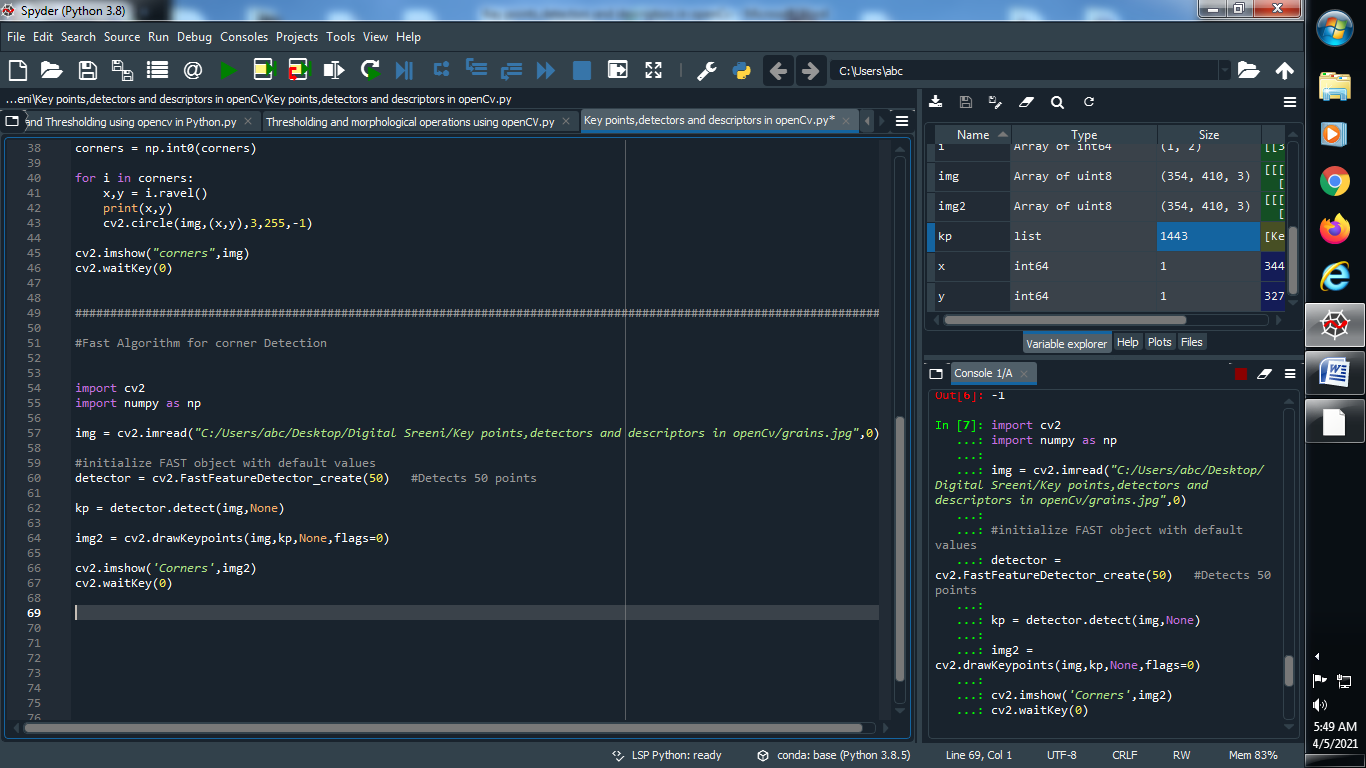
****

**→ Output :**

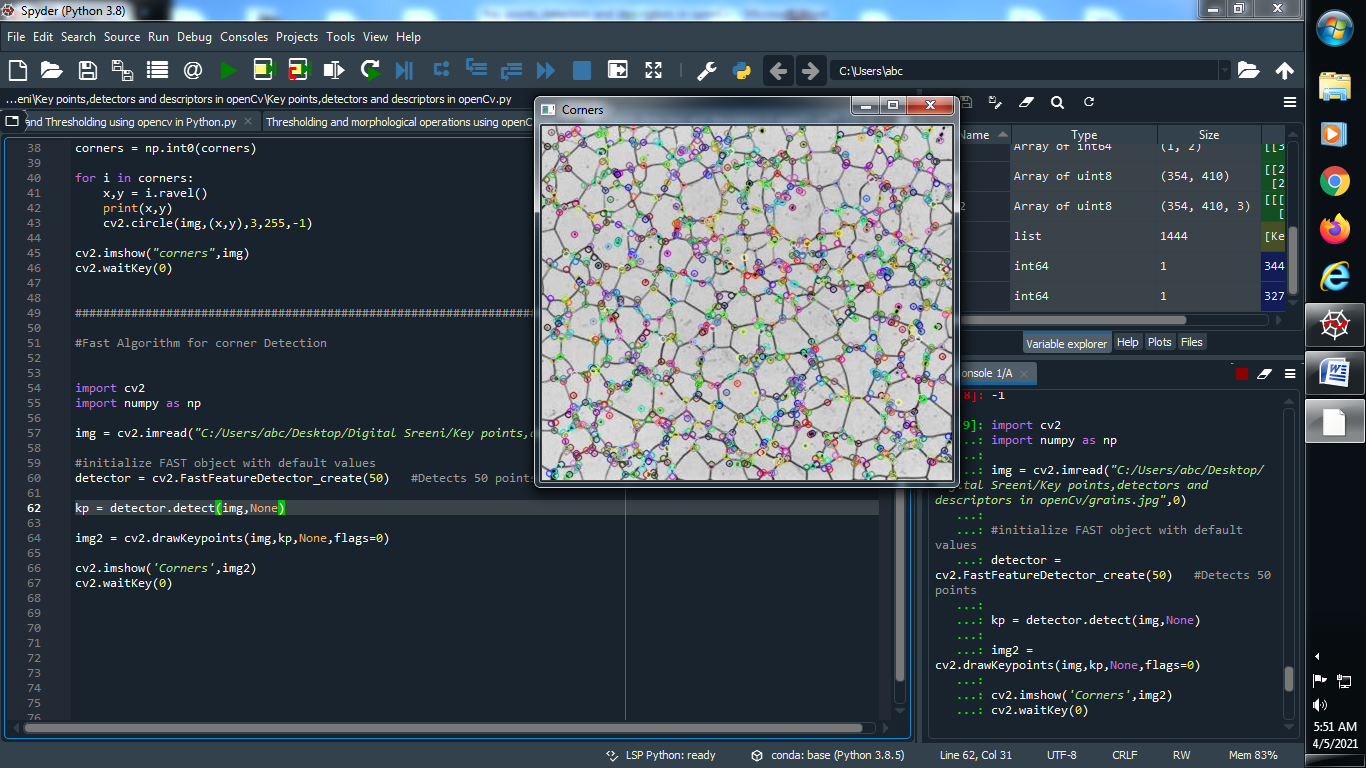
****

**Note : Above two methods harris and Shit-Tomasi both are keypoints of OpenCv.**

**(3) Fast Algorithm for corner Detection :**

****

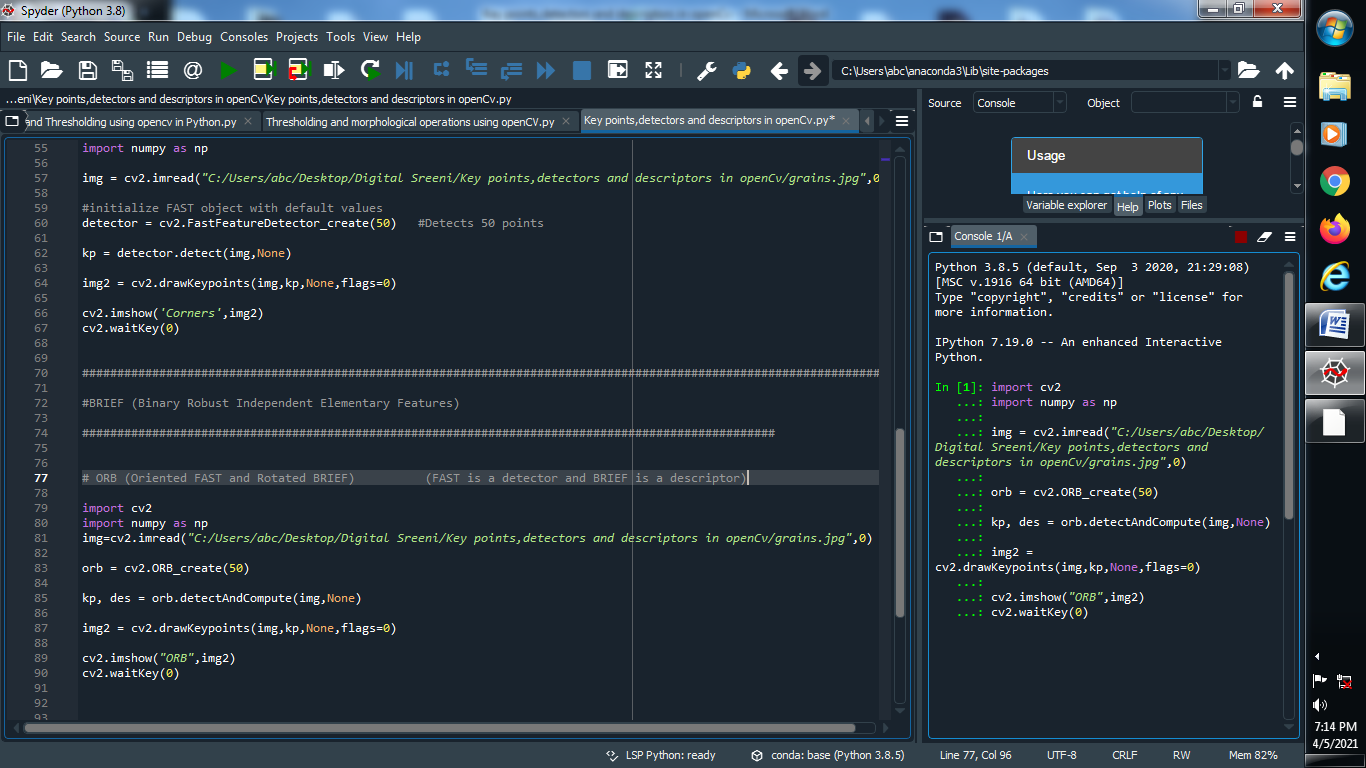
**→ Output :**

****

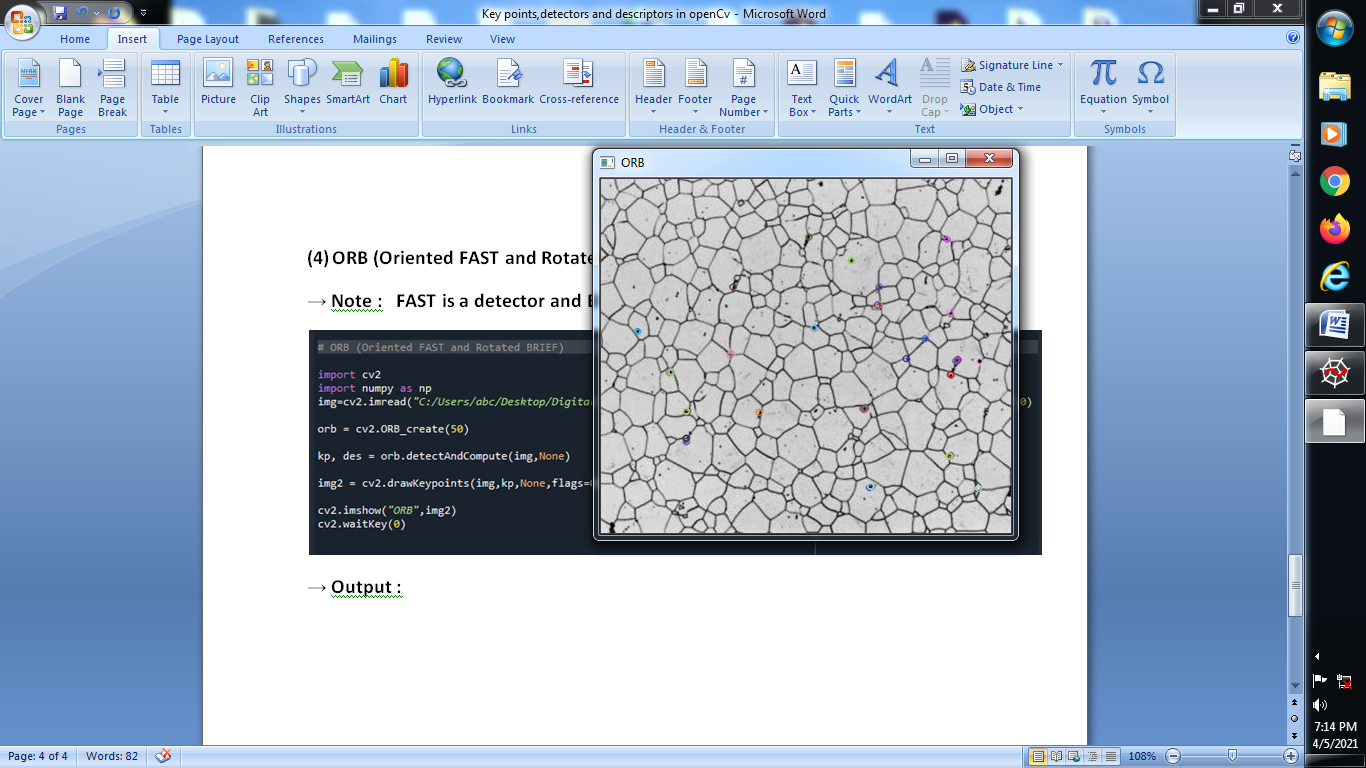
**Note : Fast Algorithm for corner Detection is feature detector .**

**(4)** **ORB (Oriented FAST and Rotated BRIEF) :**

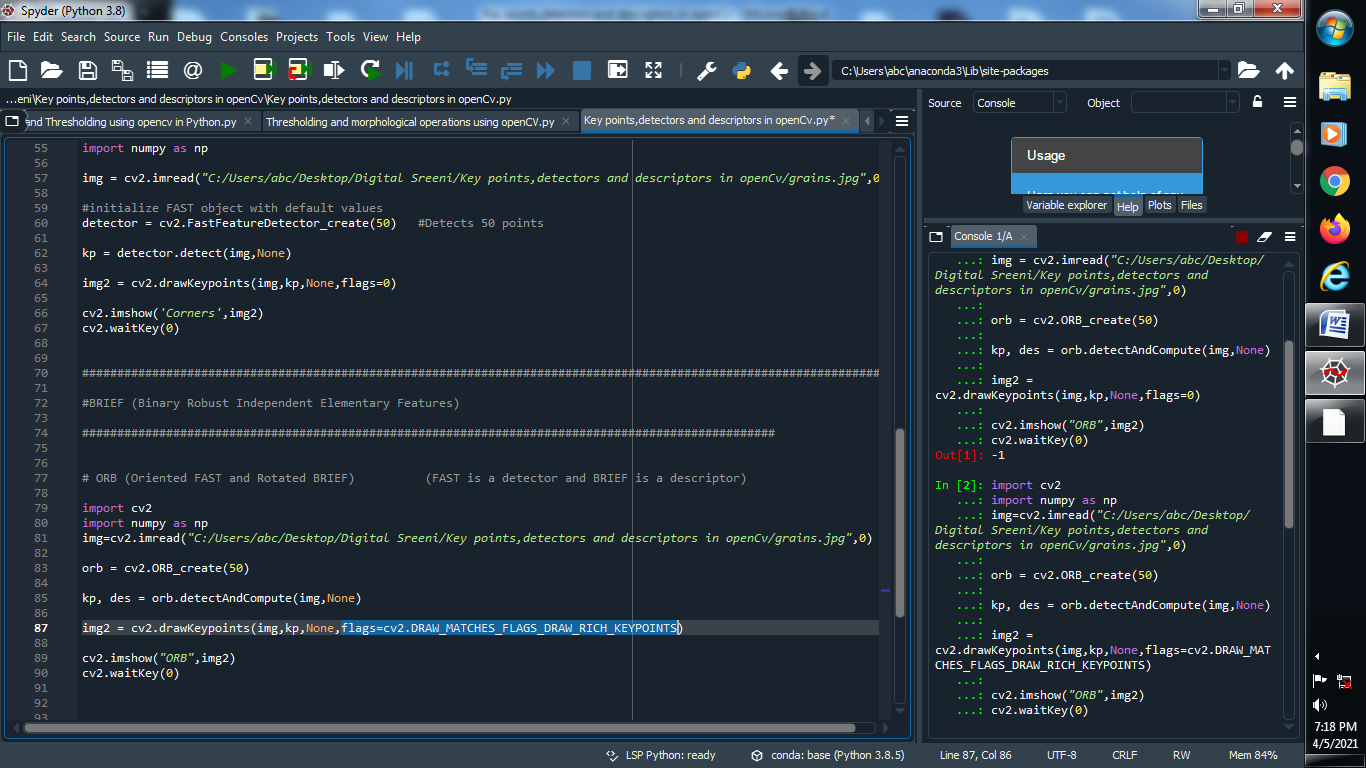
**→ Note : FAST is a detector and BRIEF is a descriptor.**

****

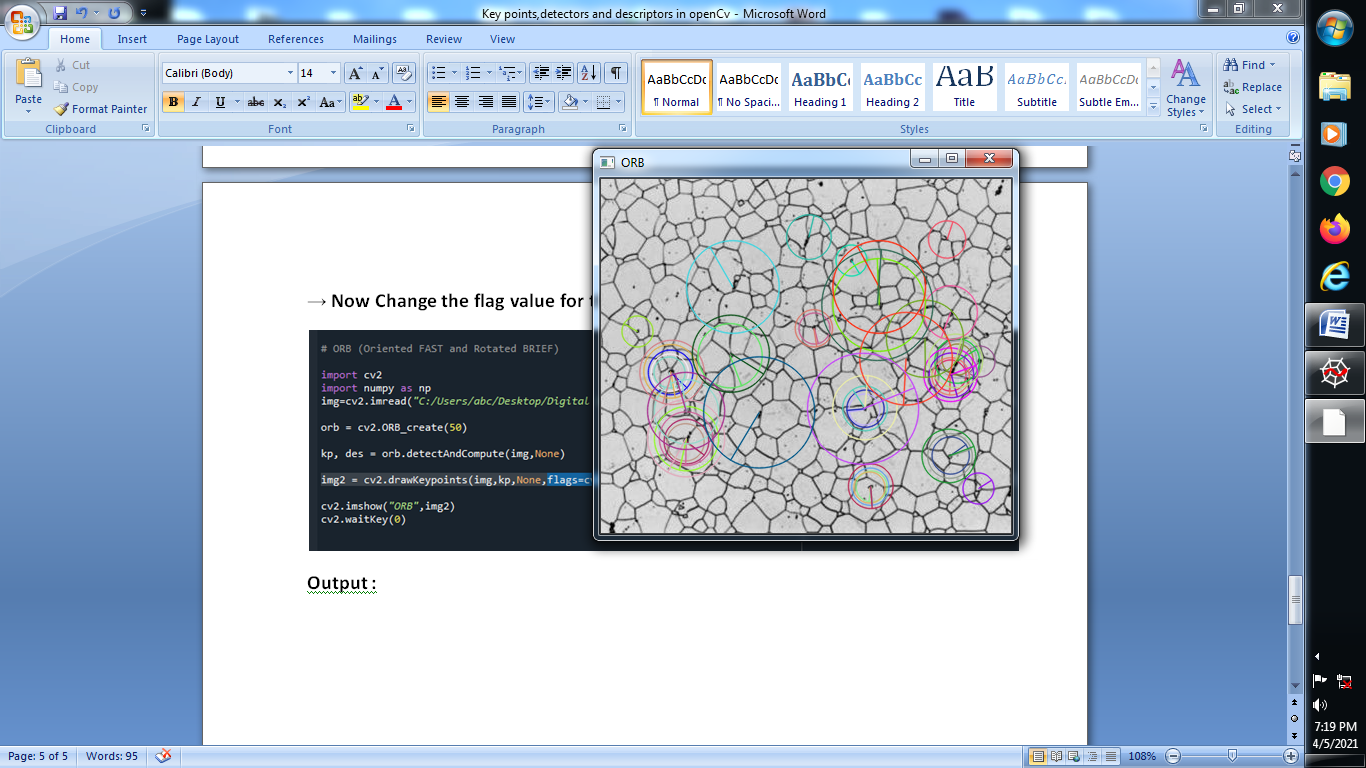
**→ Output :**

****

**→ Now Change the flag value for the better understanding :**

****

**Output :**

****